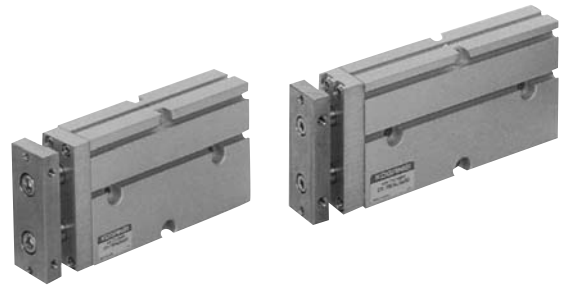
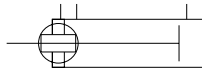


# TWIN ROD CYLINDERS B SERIES

## Double Acting Type

### Symbol



### Specifications

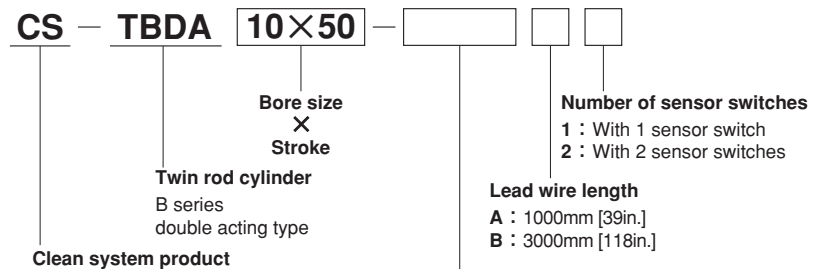
Item	Bore size mm [in.]				
	10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]
Operating type	Air				
Media	Side mount				
Operating pressure range	MPa [psi.]	0.15~0.7 [22~102]		0.1~0.7 [15~102]	
Proof pressure	MPa [psi.]	1.03 [149]			
Operating temperature range	°C [°F]	0~60 [32~140]			
Operating speed range	mm/s [in./sec.]	100~300 [3.9~11.8]			
Cushion	None	Rubber bumper			
Lubrication	Not required				
Non-rotating accuracy	±0.4°	±0.3°			
Port size	Supply port	M5×0.8			Rc1/8
	Dust collection port	M5×0.8			

### Bore Size and Stroke

Bore size	mm [in.]	
	Standard strokes	Maximum available stroke
10 [0.394]	10, 20, 30, 40, 50, 60, 70	140
16 [0.630]	10, 20, 30, 40, 50, 60, 70, 80, 90, 100	200
20 [0.787]	10, 20, 30, 40, 50, 60, 70, 80, 90, 100	200
25 [0.984]	10, 20, 30, 40, 50, 60, 70, 80, 90, 100	200
32 [1.260]	10, 20, 30, 40, 50, 60, 70, 80, 90, 100	200

Remark: Consult us for delivery of cylinders with strokes exceeding the standard.

### Order Codes



#### Sensor switch

**Blank** : Without sensor switch

**ZE135** : 2-lead wire, Solid state type with indicator lamp DC10~28V Horizontal lead wire

**ZE235** : 2-lead wire, Solid state type with indicator lamp DC10~28V Vertical lead wire

**ZE155** : 3-lead wire, Solid state type with indicator lamp DC4.5~28V Horizontal lead wire

**ZE255** : 3-lead wire, Solid state type with indicator lamp DC4.5~28V Vertical lead wire

**ZE101** : 2-lead wire, Reed switch type without indicator lamp DC5~28V, AC85~115 Horizontal lead wire

**ZE201** : 2-lead wire, Reed switch type without indicator lamp DC5~28V, AC85~115 Vertical lead wire

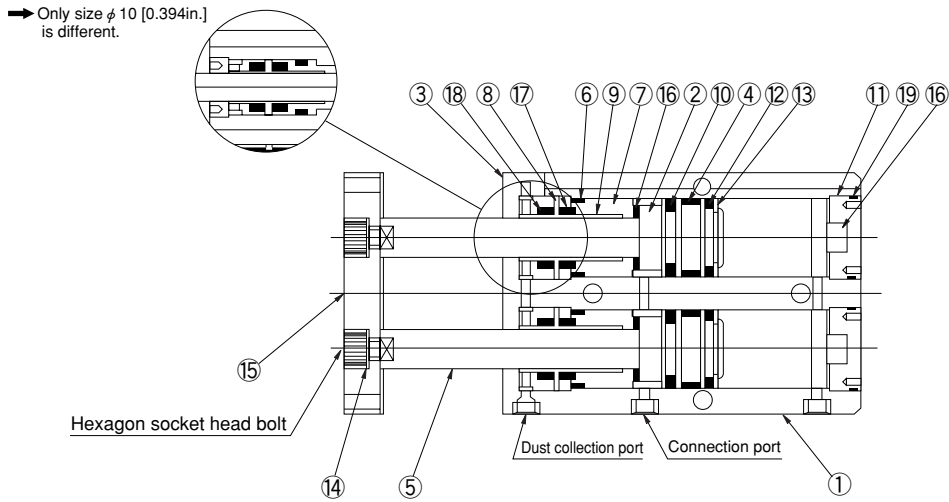
**ZE102** : 2-lead wire, Reed switch type with indicator lamp DC10~28V, AC85~115V Horizontal lead wire

**ZE202** : 2-lead wire, Reed switch type with indicator lamp DC10~28V, AC85~115V Vertical lead wire

● For details of sensor switches, see p.111~121.

Remark: In the standard cylinder, the magnet for sensor switch is built-in.

# Inner Construction and Major Parts



## Major Parts and Materials

No.	Parts	Materials
①	Cylinder body	Aluminum alloy (anodized)
②	Piston	Aluminum alloy (chromic acid anodic oxide coating)
③	Cover	Aluminum alloy (anodized)
④	Wear ring	Plastic
⑤	Piston rod	Steel (chrome plated)
⑥	Housing gasket	Synthetic rubber (NBR)
⑦	Housing	Aluminum alloy (chromic acid anodic oxide coating)
⑧	Seal holder	Mild steel (nickel plated)
⑨	Rod bushing	Plastic
⑩	Piston seal	Synthetic rubber (NBR)
⑪	Plug	Aluminum alloy (anodized)
⑫	Magnet	Plastic magnet
⑬	E-ring	Stainless steel
⑭	Washer	Steel (nickel plated)
⑮	End plate	Mild steel (nickel plated)
⑯	Bumper	φ 10, 16, 20, 25 : Synthetic rubber, φ 32 : Urethane
⑰	Rod seal	Synthetic rubber (NBR)
⑱	Dust leak prevention seal	
⑲	Plug gasket	

## Seals

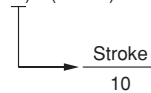
Parts	Rod seal	Piston seal	Plug gasket	Housing gasket	Dust leak prevention seal
Bore mm	Q'ty	2	2	2	2
10	PIU-6	PWP-10	1.5×9	1.5×9	PIU-6
16	PIU-8	PWP-16	1.5×15	1.5×13	PIU-8
20	PIU-10	PWP-20	1.5×19.5	1.5×17	PIU-10
25	PIU-12	PWP-25	1.5×23	1.5×22	PIU-12
32	PIU-16	PWP-32	2×31.5	2×28.5	PIU-16

## Mass

Bore size mm [in.]		Zero stroke mass <sup>Note1</sup>	Additional mass		
			Additional mass of each 10mm [0.394in.] stroke	Mass of 1 sensor switch <sup>Note2</sup>	
				ZE□□□A	ZE□□□B
10 [0.394]	Standard specification	124 [4.37]	18 [0.63]	15 [0.53]	35 [1.23]
16 [0.630]		235 [8.29]	27 [0.95]		
20 [0.787]		393 [13.86]	36 [1.27]		
25 [0.984]		584 [20.60]	51 [1.80]		
32 [1.260]		1329 [46.88]	93 [3.28]		

- Notes: 1. The above table is for the standard strokes.  
 2. There are 2 types of sensor switch lead wire lengths.  
 A: 1000mm [39in.], B: 3000mm [118in.]

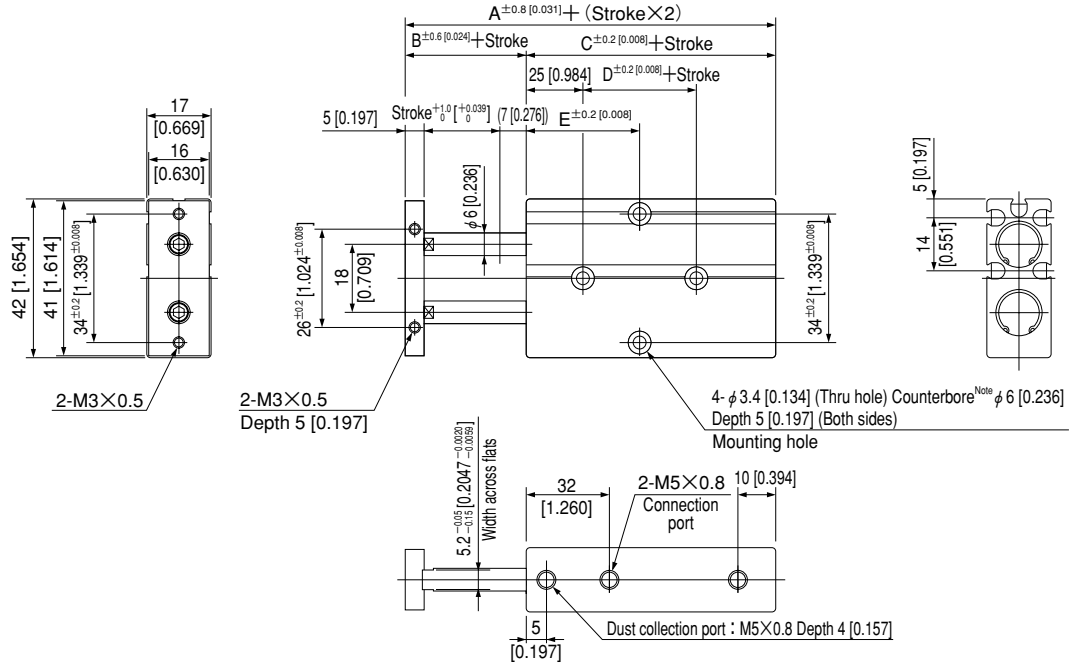
Calculation example: The mass for bore size of 20mm and stroke of 60mm with 2 sensor switches (ZC135A),  
 $393 + (36 \times 6) + (15 \times 2) = 639g$  [22.54oz.]



Dimensions mm [in.]

●  $\phi 10$

CS-TBDA10 × Stroke

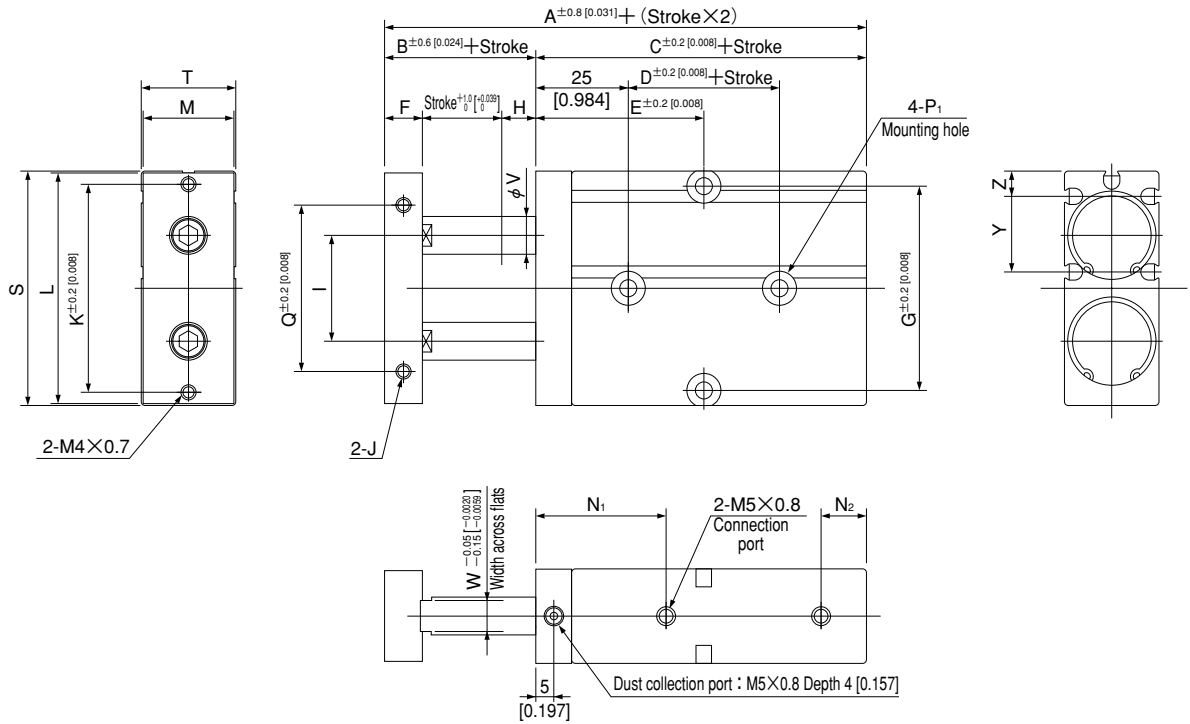


Code Stroke	A	B	C	D	E						
					10	20	30	40	50	60	70
10 [0.394]	68 [2.677]	12 [0.472]	56 [2.205]	10 [0.394]	40 [1.575]	40 [1.575]	45 [1.772]	50 [1.969]	55 [2.165]	60 [2.362]	65 [2.559]

Note: The counterbore depth is measured from the upper surface of the body.

# Dimensions mm [in.]

●  $\phi 16 \sim \phi 25$  CS-TBDA Bore size  $\times$  Stroke



Code Stroke	A	B	C	D	E										F	G	H	I	J	K	L	M	N <sub>1</sub>	N <sub>2</sub>
	10	20	30	40	50	60	70	80	90	100														
<b>16 [0.630]</b>	78 [3.071]	15 [0.591]	63 [2.480]	20 [0.787]	40 [1.575]	45 [1.772]	50 [1.969]	55 [2.165]	60 [2.362]	65 [2.559]	70 [2.756]	75 [2.953]	80 [3.150]	85 [3.346]	8 [0.315]	47 [1.850]	7 [0.276]	24 [0.945]	M4×0.7 Depth 5 [0.197]	47 [1.850]	53 [2.087]	20 [0.787]	32 [1.260]	10 [0.394]
<b>20 [0.787]</b>	88 [3.465]	20 [0.787]	68 [2.677]	20 [0.787]	45 [1.772]	45 [1.772]	50 [1.969]	55 [2.165]	60 [2.362]	65 [2.559]	70 [2.756]	75 [2.953]	80 [3.150]	85 [3.346]	10 [0.394]	55 [2.165]	10 [0.394]	28 [1.102]	M4×0.7 Depth 5 [0.197]	55 [2.165]	61 [2.402]	24 [0.945]	35 [1.378]	12 [0.472]
<b>25 [0.984]</b>	91 [3.583]	19 [0.748]	72 [2.835]	30 [1.181]	50 [1.969]	50 [1.969]	55 [2.165]	60 [2.362]	65 [2.559]	70 [2.756]	75 [2.953]	80 [3.150]	85 [3.346]	90 [3.543]	10 [0.394]	66 [2.598]	9 [0.354]	34 [1.339]	M4×0.8 Depth 6 [0.236]	66 [2.598]	72 [2.835]	29 [1.142]	40 [1.575]	12 [0.472]

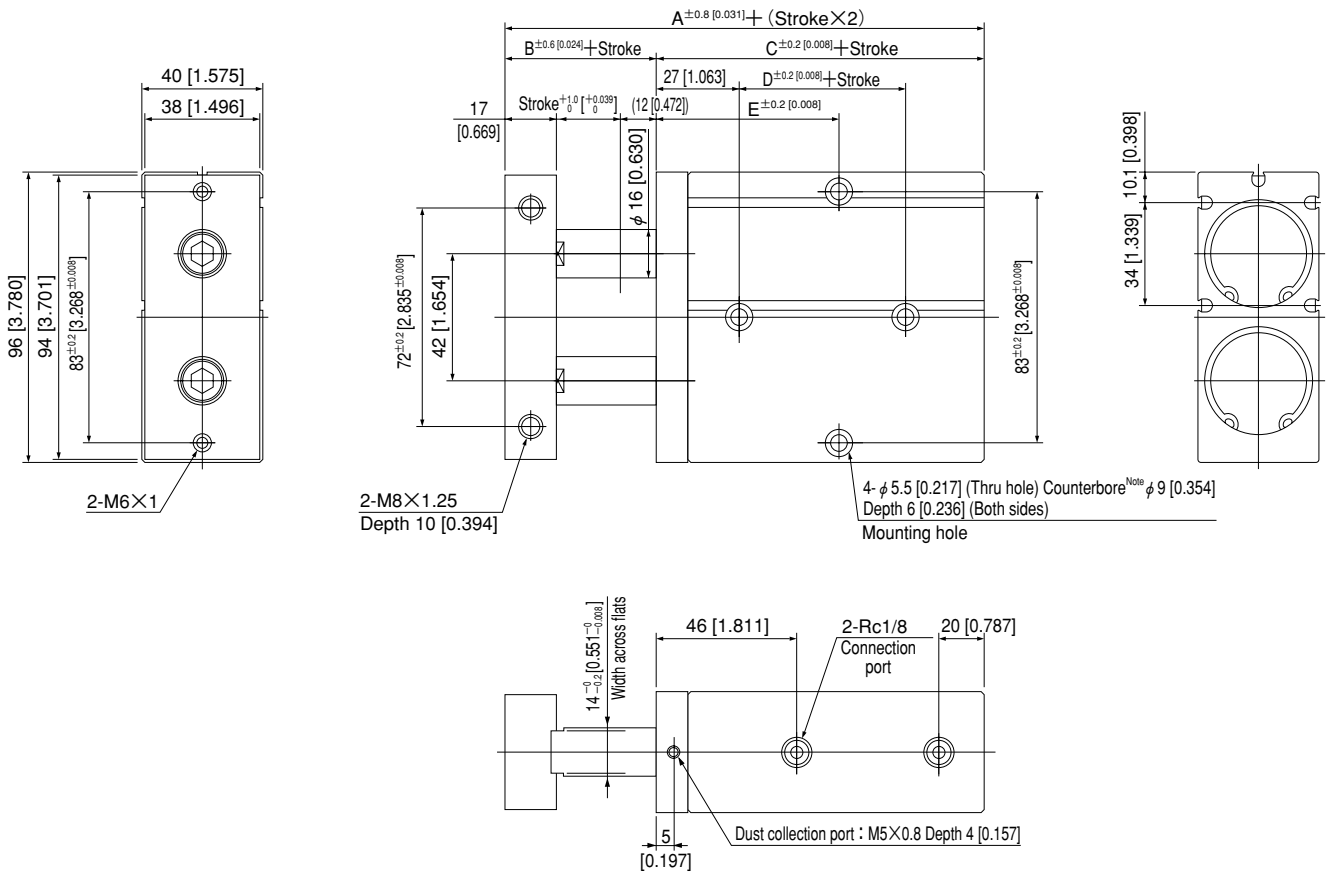
Bore	Code	P <sub>1</sub> Note	Q	S	T	V	W	Y	Z
<b>16 [0.630]</b>		$\phi 4.5 [0.177]$ (Thru hole) Counterbore $\phi 8 [0.315]$ Depth 5.5 [0.217] (Both sides)	34 [1.339]	54 [2.126]	21 [0.827]	8 [0.315]	6.2 [0.244]	18.5 [0.728]	5.7 [0.224]
<b>20 [0.787]</b>		$\phi 4.5 [0.177]$ (Thru hole) Counterbore $\phi 8 [0.315]$ Depth 5.5 [0.217] (Both sides)	44 [1.732]	62 [2.441]	25 [0.984]	10 [0.394]	8.2 [0.323]	20 [0.787]	6.8 [0.268]
<b>25 [0.984]</b>		$\phi 4.5 [0.177]$ (Thru hole) Counterbore $\phi 9 [0.354]$ Depth 6 [0.236] (Both sides)	56 [2.205]	73 [2.874]	30 [1.181]	12 [0.472]	10.2 [0.402]	22.5 [0.886]	8.3 [0.327]

Note: The counterbore depth is measured from the upper surface of the body.

# Dimensions mm [in.]

●  $\phi 32$

CS-TBDA32 × Stroke



Code Stroke	A	B	C	D	E									
					10	20	30	40	50	60	70	80	90	100
32 [1.260]	118 [4.646]	30 [1.181]	88 [3.465]	35 [1.378]	55 [2.165]	60 [2.362]	65 [2.559]	70 [2.756]	75 [2.953]	80 [3.150]	85 [3.346]	90 [3.543]	95 [3.740]	100 [3.937]

Note: The counterbore depth is measured from the upper surface of the body.

# TWIN ROD CYLINDERS B SERIES

## Sensor Switches

### Order Codes

CS —  —  — TBDA

Clean system product

#### Lead wire length

A : 1000mm [39in.]  
B : 3000mm [118in.]

#### Twin rod cylinder B series

with sensor switch mounting screw  
for  $\phi$  10 [0.394in.] ~  $\phi$  32 [1.260in.]

#### Sensor switch

<b>ZE135</b> — 2-lead wire, Solid state type with indicator lamp	DC10~28V	Horizontal lead wire	<b>ZE155</b> — 3-lead wire, Solid state type with indicator lamp	DC4.5~28V	Horizontal lead wire
<b>ZE235</b> — 2-lead wire, Solid state type with indicator lamp	DC10~28V	Vertical lead wire	<b>ZE255</b> — 3-lead wire, Solid state type with indicator lamp	DC4.5~28V	Vertical lead wire
<b>ZE101</b> — 2-lead wire, Reed switch type without indicator lamp	DC5~28V AC85~115V	Horizontal lead wire	<b>ZE102</b> — 2-lead wire, Reed switch type with indicator lamp	DC10~28V AC85~115V	Horizontal lead wire
<b>ZE201</b> — 2-lead wire, Reed switch type without indicator lamp	DC5~28V AC85~115V	Vertical lead wire	<b>ZE202</b> — 2-lead wire, Reed switch type with indicator lamp	DC10~28V AC85~115V	Vertical lead wire

● For details of the sensor switches, see p.111 ~ 121.

### Sensor Switch Operating Range, Response Differential, and Maximum Sensing Location

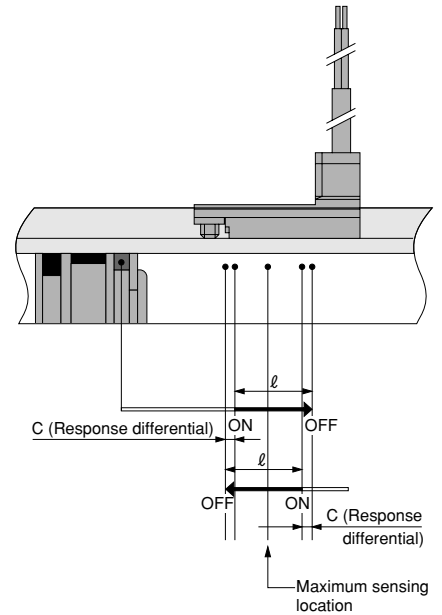
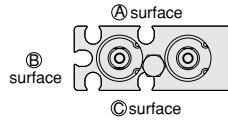
#### ● Operating range: $\ell$

The distance the piston travels in one direction, while the switch is in the ON position.

#### ● Response differential: C

The distance between the point where the piston turns the switch ON and the point where the switch is turned OFF as the piston travels in the opposite direction.

#### ● Sensor switch mounting surface



#### ● Solid state type

Item	Mounting surface	Bore size				
		10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]
Operating range : $\ell$	A and C surface	2.5~6 [0.098~0.236]			2.5~6.5 [0.098~0.256]	5~12 [0.197~0.472]
	B surface	2.5~4 [0.098~0.157]	2~4.5 [0.079~0.177]		2.5~5.5 [0.098~0.217]	4~9 [0.157~0.354]
Response differential : C	—	1.0 [0.039] or less	1.2 [0.047] or less		1.5 [0.059] or less	2.0 [0.079] or less
Maximum sensing location <sup>Note</sup>	—	6 [0.236]				

Remark: The above table shows reference values.

Note: The maximum sensing location is the distance from the end of the switch opposite to the lead wire.

#### ● Reed switch type

Item	Bore size	Bore size				
		10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]
Operating range : $\ell$	—	6~8.5 [0.236~0.335]		6~8 [0.236~0.315]	7~9.5 [0.276~0.374]	12~16.5 [0.472~0.650]
Response differential : C	—	1.5 [0.059] or less				2.5 [0.098] or less
Maximum sensing location <sup>Note</sup>	—	10 [0.394]				

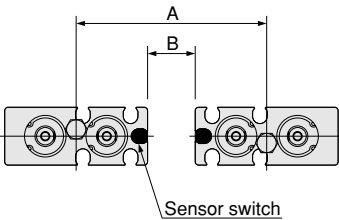
Remark: The above table shows reference values.

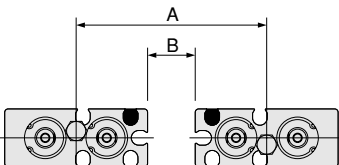
Note: The maximum sensing location is the distance from the end of the switch opposite to the lead wire.

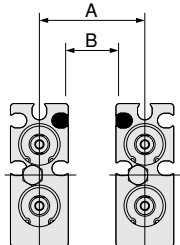
## When Mounting Cylinders with Sensor Switches in Close Proximity

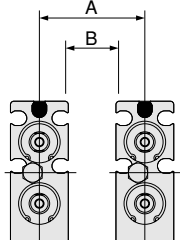
When mounting cylinders in close proximity, install the cylinder so that it should exceed the values in the table below.

mm [in.]

Status of mounting in close proximity	Code	Bore size Type	10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]
				<b>A</b>	Solid state type	53 [2.087]	66 [2.598]
Reed switch type	48 [1.890]	60 [2.362]	68 [2.677]		81 [3.189]	109 [4.291]	
	<b>B</b>	Solid state type	11 [0.433]	12 [0.472]	11 [0.433]	14 [0.551]	23 [0.906]
		Reed switch type	6 [0.236]			8 [0.315]	13 [0.512]

	<b>A</b>	Solid state type	47 [1.850]	59 [2.323]	65 [2.559]	77 [3.031]	107 [4.213]	
		Reed switch type	42 [1.654]	54 [2.126]	62 [2.441]	73 [2.874]	96 [3.780]	
	<b>B</b>	Solid state type	5 [0.197]			3 [0.118]	4 [0.157]	11 [0.433]
		Reed switch type	0 [0]					

	<b>A</b>	Solid state type	28 [1.102]	33 [1.299]	36 [1.417]	44 [1.732]	65 [2.559]
		Reed switch type	22 [0.866]	27 [1.063]	30 [1.181]	37 [1.457]	53 [2.087]
	<b>B</b>	Solid state type	11 [0.433]	12 [0.472]	11 [0.433]	14 [0.551]	25 [0.984]
		Reed switch type	5 [0.197]	6 [0.236]	5 [0.197]	7 [0.276]	13 [0.512]

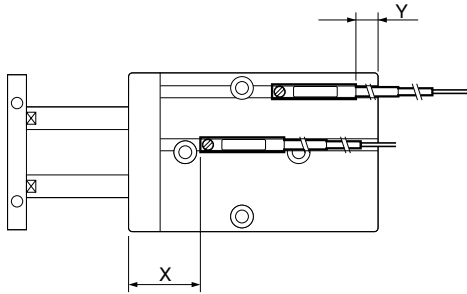
	<b>A</b>	Solid state type	21 [0.827]	24 [0.945]	25 [0.984]	30 [1.181]	44 [1.732]
		Reed switch type	17 [0.669]	21 [0.827]	25 [0.984]	30 [1.181]	40 [1.575]
	<b>B</b>	Solid state type	4 [0.157]	3 [0.118]	0 [0]		4 [0.157]
		Reed switch type	0 [0]				

Remark: For mounting in configurations other than the above, consult us.

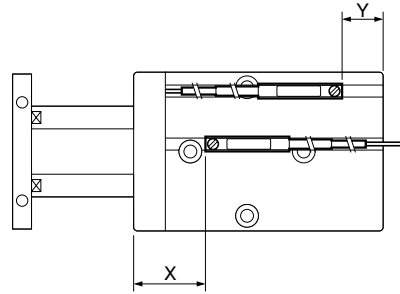
## Mounting Location of End of Stroke Detection Sensor Switch

When the sensor switch is mounted in the locations shown below (figures in the tables are reference values), the magnet comes to the maximum sensing location of the sensor switch at the end of the stroke.

■ When the lead wire is pulled from the head side.



■ When the lead wire of the head side detection sensor switch only is pulled from the rod side.



### ● Solid state type

mm [in.]

Code \ Bore	10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]
<b>X</b>	37.5 [1.476]	43.5 [1.713]	47.5 [1.870]	52.5 [2.067]	62 [2.441]
<b>Y</b>	-3.5 [-0.138]	-2.5 [-0.098]	-1.5 [-0.059]	-2.5 [-0.098]	4 [0.157]

### ● Reed switch type

mm [in.]

Code \ Bore	10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]
<b>X</b>	33.5 [1.319]	39.5 [1.555]	43.5 [1.713]	48.5 [1.909]	58 [2.283]
<b>Y</b>	0.5 [0.020]	1.5 [0.059]	2.5 [0.098]	1.5 [0.059]	8 [0.315]

### ● Solid state type

mm [in.]

Code \ Bore	10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]
<b>X</b>	37.5 [1.476]	43.5 [1.713]	47.5 [1.870]	52.5 [2.067]	62 [2.441]
<b>Y</b>	6.5 [0.256]	7.5 [0.295]	8.5 [0.335]	7.5 [0.295]	14 [0.551]

### ● Reed switch type

mm [in.]

Code \ Bore	10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]
<b>X</b>	33.5 [1.319]	39.5 [1.555]	43.5 [1.713]	48.5 [1.909]	58 [2.283]
<b>Y</b>	2.5 [0.098]	3.5 [0.138]	4.5 [0.177]	3.5 [0.138]	10 [0.394]